RS232 Basics:

Remote Lab instructions

Serial RS232

V1

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Instructions RS232 Basics

Getting Started

- Logon to Electromeet (Follow the How to Connect to Remote Labs_Electromeet_HTML5_Remote_Lab instructions document)
- The software is installed on Remote Lab 5

Hardware:

As you will be doing this exercise by way of a remote lab please note that all the hardware is already set up and connected to **Remote Lab 5.** Any other remote lab will not have the correct hardware setup.

Software & Hardware used:

The lab was set up with the following hardware:

- Laptop with at two USB ports
- 1x MOXA UPort 1110 USB-to-serial (RS-232) adapter
- 1x 9-pin D-type female to 25-pin D-type male adapter plug ('straight') (DB-9F/DB-25M)
- 1x breakout box
- 1x PicoScope 2204 USB oscilloscope with probes

The following software has been installed:

- Listen32 (for sending characters via the COM port)
- Picoscope6 software





RS232

The objective of this exercise is to give you an understanding of how asynchronous serial data communications operate, using a breakout box on the COM port of a laptop computer. Since most laptops nowadays do not have physical COM ports, we will use a USB-to-Serial converter to accomplish this. The MOXA adapter used actually has on on-board UART (Universal Asynchronous receiver Transmitter), so the UART has simply been relocated from the motherboard to the USB adapter. The output of the serial port will be monitored by means of a PC-based oscilloscope.

1.0 Implementation

1.1 Basic port setup

As you will be doing this exercise by way of a remote lab, all of the equipment will already be set up, but please read the instructions below to familiarize yourself with the procedure.

Despite the fact that the drivers have already been installed, it is important that you verify the COM port allocated to the UPort 1110.

The USB to serial RS232 hardware being used is shown in the images below:



The purpose of the three LEDs are as follows:

Name	Description				
Active	This LED indicates normal operation. If the driver is installed correctly and the adaptor is plugged into a functioning USB port, the Active LED will light up and remain on. If the LED does not light up, there may be a problem with the adaptor, the driver installation, or PC configuration.				
TxD	This LED blinks when the adaptor transmits data through its COM port.				
RxD	This LED blinks when the adaptor receives data through its COM port.				

If the red LED on the converter does not light up, or a yellow exclamation mark shows up against the UPort 1110 entries in the Device Manager, it could be that the driver settings have been altered.

Since this is a remote setup, assume that the LED lights up.

You can confirm the COM port to which the serial device is mapped, by following the below steps:

Click: Start->Control Panel ->System->Hardware->Device Manager.

Locate the entry that reads: 'Multi-port serial adapters' and expand it to show the UPort 1110.



Double-click (or right-click->Properties) on 'UPort 1110' to obtain its properties window.

PUICII	to Properties		2 24				4
General	Ports Configuration	Driver	Details				
»Ú	UPort 1110						
	Device type:	Multi-po	rt serial ad	apters			
	Manufacturer:	Moxa T	echnologie	es Co., Lto	ł.		
	Location:	Location	n 0 (NPort	U1110)			
Devic	e status					-	
lf you start	are having problems the troubleshooter.	with this	: device, c	lick Trout	oleshoot to	2	
				Trout	leshoot		
Device	usage:			1			
Use th	s device (enable)					~	

Select the 'Ports Configuration' tab and note the COM port that has been allocated to the UPort 1110.



Please do not change it.

(Should a user wish to change to another port number, this can be accomplished by clicking on 'Port Setting' and selecting an appropriate one. On a machine without any COM ports any one could be selected, but on machines with an existing COM ports (typically COM1) you have to select a different one to avoid conflicts)

As an additional check, go back to the Device Manager and locate 'MOXA USB Serial Port (COM2)' (this is the COM port number we selected earlier). Double-click (or right-click->Properties) on the MOXA entry to obtain the MOXA serial port properties. Select the 'Port Settings' tab and check the Universal Asynchronous Receiver Transmitter (UART) settings. These settings can, however, be overwritten by application programs such as Listen32.



UPort 1110 Properties
General Ports Configuration Driver Details
Port COM No. Fast Flush Interface
1
Port Setting

The Moxa 1110 settings are now complete (this should already be done on the remote lab computer so no changes should need to be made)

1.2 Prepare to send characters

1. Run Listen32 by clicking on the desktop icon or on the taskbar at the bottom of the screen.



Listen32 will open up:

🔏 Listen 32Serial Data Line Monitor	
File Edit View Setup Help	
<u>X1 X2 X3 X4 X5</u>	
BX	
GN	GND 2000
	listen
For Help, press F1	Trap Buffer Empty Trigger OnSafe Filters OFF

2. Click Setup->Hardware:



3. Then set the UART parameters for the appropriate COM port (COM2 in this case). Set the parameters exactly as per the following figure: 9600, 7, 0, 1.

Port Configuration	
Port 1 Port 2 Port 3 Port 4 Port 5 Port 6 Port 7 Port 8 Port 9	1
BaudRate: 9600 V DataBits: 7 V	
Control Lines	
DTR/DSR	
Cancel	

4. Next, start the port monitoring process by clicking on the green traffic light (click red to stop – remember to click green light again to start it again – the red light is shown while the connection is active).



5. The 'Begin Data Collection' window will appear. Select the appropriate port (COM2 in this case).

Begin Data C	ollection			×
Physic	al Connection	s		
Г	COMM 1	🔲 СОММ 4	🗆 СОММ 7	
L I	COMM 2	🔲 СОММ 5	🔲 СОММ 8	
Г	СОММ З	🗆 СОММ 6	🔲 СОММ 9	
	L	aunch an Applica	ition	
		DK Ca	ancel	

Listen32 is now running and the UART on the Moxa device is configured correctly Now you must confirm the idle voltage

1.3 Confirmation of idle voltages

The USB converter is connected to the breakout box by means of the DB-9/DB-25 plug. It looks like this:



Normally in a hands-on situation you would do this by observing the LEDs on the breakout box or by measuring the voltage across the two pins (TxD on pin 2, gnd on pin 7) by means of a voltmeter.

However as we are doing this remotely we can measure the TxD line idle voltage with the Picoscope.

To do this you must

6. Run the Picosope6 software. Double-click the PicoScope6 icon on the desktop of the remote computer (Remote Lab 5)



7. We can add a measurement function to the PicoScope, which will allow us to obtain a DC voltage reading. Firstly click "Measurements" at the top of the PicoScope window

Horas PicoScope 6					
<u>F</u> ile <u>E</u> dit <u>V</u> iews	<u>M</u> e	asurements	<u>T</u> ools	<u>H</u> elp	
<u>м</u> л. ш. 🖳 🦻 (<u>A</u> dd Measu	rement		8.001 kS 🕀 📢 32 of 32 🕪 🧭
A. ±10 V ∨ DC		<u>E</u> dit Measu	rement		
1 0.0		<u>D</u> elete Mea	surement		
V		Grid <u>F</u> ont Siz	ze 7	\checkmark	
8.0	\checkmark	<u>C</u> olumn Au	to-width		
C 0					

- 8. Click "Add Measurement"
- 9. This will bring up the "Add Measure Window"

Add Measurement	— ×-
Select the channel to measure	ОК
Select the type of measurement	Cancel
AC RMS	Help
Choose which section of the graph will be measured	
Whole trace	Advanced

10. From the Type of measurement selection field select "DC Average"

PicoScope 6	
<u>File Edit Views M</u> easurements <u>T</u> ools <u>H</u> elp	
🔁 Л Ш Ц 🤌 🦻 🟠 20 µs/div 💛 🛛 x 1 🕀 8.001 kS 🕀 🤇	🚺 32 of 32 🚺 🧭
A ₁ ±10 V ∨ DC ∨ B ₁ Off ∨ DC ∨ A	
80	
0.0	
6.0	
Add Measurement	
4.0 Select the channel to measure	ОК
20	Cancel
Select the type of measurement	
0.0 AC RMS V	Help
Cycle Time DC Average	Advanced
-2.0 Duty Cycle Falling Rate	Advanced
-4 0 Frequency	
High Pulse Width	
-6.0 Maximum	
Minimum Peak To Peak	
-8.0 Rise Time Rising Rate	
-10.0	
0.0 20.0 40.0 60.0 80.0 100.0 120.0 140.0 x1.0 μs	160.0 180.0 200.0
Trigger None 🔽 🖈 🛛 🗸 🔍	20 % 🗘 🏷

- -6.0 -8.0 10.Q 20.0 40.0 60.0 100.0 120.0 160.0 180.0 200.0 00 140.0 (1.0 US Name /hole tra 5.325 V -5.331 \ Trigger None V JI 8 1 \sim
- 11. Then Click OK. This will add the measuring function to the bottom of the PicoScope

- 12. You can then read the average DC voltage level.
- 13. Question: What is the average DC voltage on the TxD line when it is idling? State the answer in your assignment (rounded to 2 decimal places).
- 14. Instruction: Take a screenshot of this and paste it into your assignment.

1.4 Transmitting a single character and then capturing it on the Picosocpe

You now must transmit a single character and capture the output of the TxD line on the Picoscope.

NOTE: THIS IS A TRAP FOR THE UNWARY. The Start/Stop buttons on the PicoScope complement every time you click on them. So, if the PicoScope has stopped capturing, and you click twice on the Start button, you are still in 'stop' mode. However, if you observe the backgrounds of the Stop and Start buttons you will notice that they change from

00 vellow to blue when 'true'.

We already have the PicoScope running but now must change the configuration to capture the waveform. The PicoCcope settings should be as follows:

- Trigger: Single trigger, Channel A, rising edge
- X-axis: 200 microseconds per division •
- Magnification: X1
- Y-axis full scale: +/-10V
- Coupling: DC •
- Tigger level: 0V
- Pre-trigger: 20%

Here is how we change to settings

15. On the Picoscope under the trigger Field (at the bottom of the screen) select "Single"



16. Set the pre-trigger to 20%. This defines the point (from left to right across the X axis) where the leading edge of the 'start' bit (on which you are triggering) will appear



17. At the top of the PicoScope under the Time/div field select 200 $\mu s/div$

Horoscope 6	
<u> </u>	asurements <u>T</u> ools <u>F</u>
📶 🔟 🔟 🥖 🏠 🗌	20 µs/div 🔽 🛛 🗙 1
Auto 🔽 DC	10 µs/div 20 µs/div
■ 50.0 ₅	50 µs/div
mV	200 µs/div
40.0	1 ms/div
30.0	2 ms/div 5 ms/div
	10 ms/div 20 ms/div ≡
20.0	50 ms/div
10.0	200 ms/div
1. Ishlaturata	1 s/div
0.0111111111111	2 s/div
100 In the second s	10 s/div 20 s/div

18. Now click the green "Start Capturing" icon (green Icon at the bottom left of the Picoscope window)



The Picoscope is now ready to capture the character we are about to transmit

- 19. We already have Listen32 running (it will be in the tool bar at the bottom of the screen if the window is not already on screen)
- 20. On the Listen32 window click Edit->Transmit string. The 'Define Transmit Strings' window will appear.

🔏 Lis	ten32Serial Data Line Monitor	
File	Edit View Setup Help	
X1	Copy to Clipboard Clear Buffer Reset	<u>?</u>
	Find Calc Checksum Transmit String	

• The "Define Transmit Strings" window will now appear

De	efine Transmit Strings	x
[String 1 String 2 String 3 String 4 String 5	
	Port C1 @ 2 C 3 C 4 C 5 C 6 C 7 C 8 C 9	
	F	
	Enter non-printing characters as: Decimal [000] to [255]	
	[Done]	

- 21. Select String 1 for the appropriate port (check that port2 is got a dot in), and enter upper case F.
- 22. Click "Send Now" to transmit. The transmission should be captured on the PicoScope now. (NOTE: in case the Send Now button is greyed out, simply go to step 4 and stop / start the serial connection again)
- 23. Select the PicoScope again (remember it will be on the tool bar at the bottom of the screen if not on screen) And you should have a wave form similar to the one below:



The voltage levels are around -5.5V, +5.5V due to the specific machine to which the converter is connected. For laptops, these voltages seem to vary from around +/- 5.5V to +/- 9V and they are often not perfectly symmetrical with respect to ground.

Instruction: Take a screenshot of this waveform, and paste it into your assignment.

Question: What is the actual bit rate in bits per second? This is also referred to as the baud rate (bit rate = baud rate for RS-232). You do this by first measuring the width of one bit on the oscilloscope (in milliseconds) and then inverting that to get the answer in bps. Show your calculations

Question: What is the effective data rate? Not all the bits in the frame carry information. Calculate the effective data rate by taking your answer in (a) above, and multiplying it with the ratio of actual information bits to total data bits in the frame.

Hint: For the example above (letter F at 9600,7,0,1) the parity bit is the last 'positive pulse' at around 0.9 mS on the x-axis.

End of Exercise