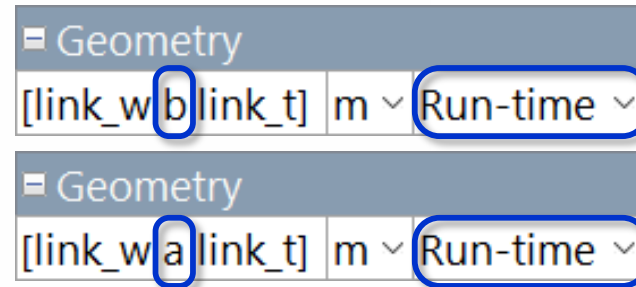
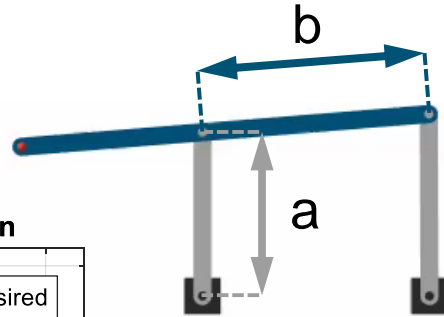
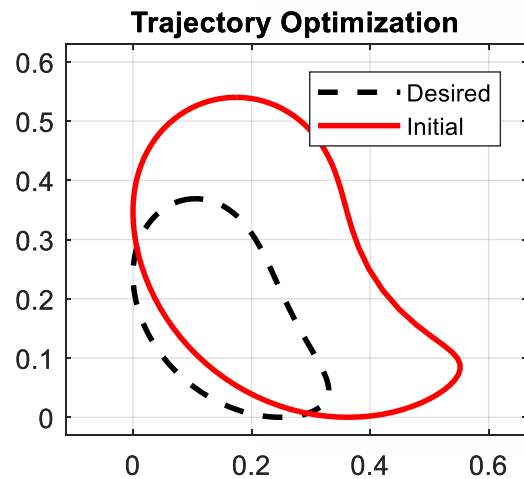


Four Bar Trajectory Optimization

Model:



Challenge: Tune lengths of a four-bar linkage so that the tip follows a desired trajectory.

Solution: Use [Simscape Multibody](#) and [MATLAB](#) optimization algorithms to automatically tune the mechanical design

