

## ANSWER KEY - LABORATORY EXERCISE 17

### CHARACTERISTICS OF MULTIPLICATIVE FEEDFORWARD CONTROL

#### 2. FEEDFORWARD CONTROLLER SETUP

Feedforward tuning:

$$T_{ld} = 7.5$$

$$T_{lg} = 10.2$$

$$T_{dt} = 1.75$$

Feedback tuning:

$$\text{Gain} = 1.0$$

$$\text{Reset} = 10.8 \text{ minutes/repeat}$$

$$\text{Fuel Flow } 28.0 \text{ KCFH} = 28\%$$

$$\text{Process Flow } 300 \text{ GPM} = 75\%$$

$$\text{Ratio } (28/75) = 0.3733$$

$$\text{Ratio, converted to percent} = 37.33\%$$

$$\text{Primary controller output} = 37.33\%$$

$$\text{Primary controller output, after changing KI to 2.0} = 18.67\%$$

$$\text{New Primary controller Gain} = 0.5$$

#### 3. TESTING THE CONTROL LOOP

$$\text{Is the response to load change OK?} = \text{Yes}$$

$$\text{Is the response to SP change OK?} = \text{Yes}$$

At each step,..., response to load  
change OK? Yes

At high process flow rate ...  
response to SP change OK? Yes

Decrease process flow rate, one step at a time.

At each step, .... going unstable? No

Additive feedforward? Became unstable

Response as good as .... at 75% load? No