

**ANSWER KEY - LABORATORY EXERCISE 9
PID TUNING FROM OPEN LOOP TESTS**

2. OPEN LOOP TESTING

NOTE: Some persons may use the GENERIC2 model for Laboratory Exercises 3 and 4, rather than the suggested GENERIC model. Hence, data is given for both models.

	PROCESS MODEL					
	GENERIC			GENERIC2		
Process Gain	1.5			1.5		
Dead Time	2.0 mins			4.0 mins		
Time Constant	7.0 mins			8.0 mins		
	P	PI	PID	P	PI	PID
Gain (Kc)	2.33	2.1	2.8	1.33	1.2	1.6
Prop Band (PB)	43%	48%	36%	75%	83%	63%
Integ Time (Ti) Mins/Rpt	___	6.67	4.0	___	13.3	8.0
Reset Rate Rpts/Min	___	0.15	0.25	___	0.075	0.125
Deriv Time (TD)	___	___	1.0	___	___	2.0
Decay Ratio	0.10	0.183	0.062	0.33	0.385	0.174
Period, mins	12.6	14.0	15.0	21.0	24.0	18.0
Period/Integ Time	___	2.1	___	___	1.80	___

<p>For the P-only controller, the eventual settling value was 313.9, compared with a Set Point of 325. Therefore the decay ratio was figured from overshoots above 313.9.</p>	<p>For the P-only controller, the eventual settling value was 308.0, compared with a Set Point of 325. Therefore the decay ratio was figured from overshoots above 308.0.</p>
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Set Point response: PID

Load (disturbance) response: PID

Added process measurement noise:

Measurement noise causes greatly amplified controller output movement when using derivative.

Added measurement filter:

Effect of derivative and measurement noise on controller output is somewhat diminished.